

**IN THE ABSTRACT:**

Kindly replace the Abstract with the following amended Abstract:

A method of clamping a rotationally symmetrical body (10) for the purpose of machining, in which method the body (10), with its first side (12), is pulled by means of a tensile force (F1), which acts in extension of the rotation axis (19, 19') of the body (10) on the first side (12) of the body (10), against a supporting element (72) having a centering effect and device for clamping a rotationally symmetrical body **[[10]]** for the purpose of machining, which device ~~comprises~~ includes a supporting element **[[72]]**, against which the body **[[10]]** can be pulled, and a tie rod **[[64]]** which can act on and pull the body **[[10]]**, to be clamped, axially and concentrically to the rotation axis (19, 19') of the latter. The mounting of the tie rod **[[64]]** is designed in such a way that the tie rod **[[64]]** is axially guided with radial clearance **[[66]]** for the axial pulling movement. The tensile force **[[F1]]** of the tie rod **[[64]]** is preferably adjustable. **[[A]]** The rotationally symmetrical body **[[10]]**, in particular a rotor, which, on a first side **[[12]]**, has a coupling unit **[[18]]**, which is concentric with its rotation axis **[[19]]**, and a bearing region **[[22]]** having at least three bearing surfaces **[[24]]** arranged concentrically to the rotation axis **[[19]]**.

Figure 7